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δN -formalism and superhorizon curvature perturbations

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0. Introduction

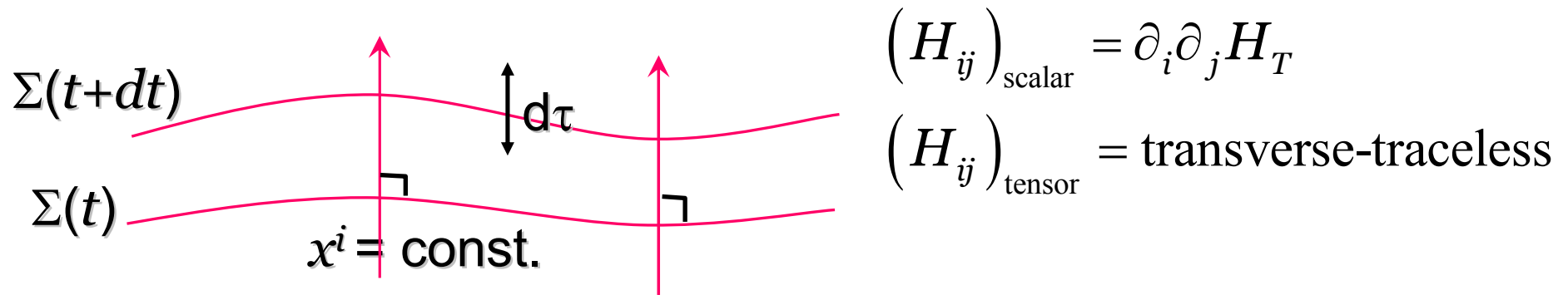
What is δN ?

- δN is the perturbation in # of e-folds counted **backward in time** from a fixed final time t_f
- t_f should be chosen such that the **evolution of the universe has become unique** by that time.
- δN is equal to **conserved NL comoving curvature perturbation** on superhorizon scales **at $t > t_f$**
- δN is essentially **independent of gravity theory**

1. Linear δN formula

- metric (on a spatially flat background)

$$ds^2 = -(1 + 2A)dt^2 + a^2(t) \left[(1 + 2\mathcal{R})\delta_{ij} + H_{ij} \right] dx^i dx^j$$



- proptime along $x^i = \text{const.}$: $d\tau = (1 + A)dt$
- curvature perturbation on $\Sigma(t)$: $\mathcal{R} \iff \overset{(3)}{\mathcal{R}} = -\frac{4}{a^2} \overset{(3)}{\Delta} \mathcal{R}$
- expansion (Hubble parameter): $\tilde{H} = H(1 - A) + \partial_t \left[\mathcal{R} + \frac{1}{3} \overset{(3)}{\Delta} H_T \right]$

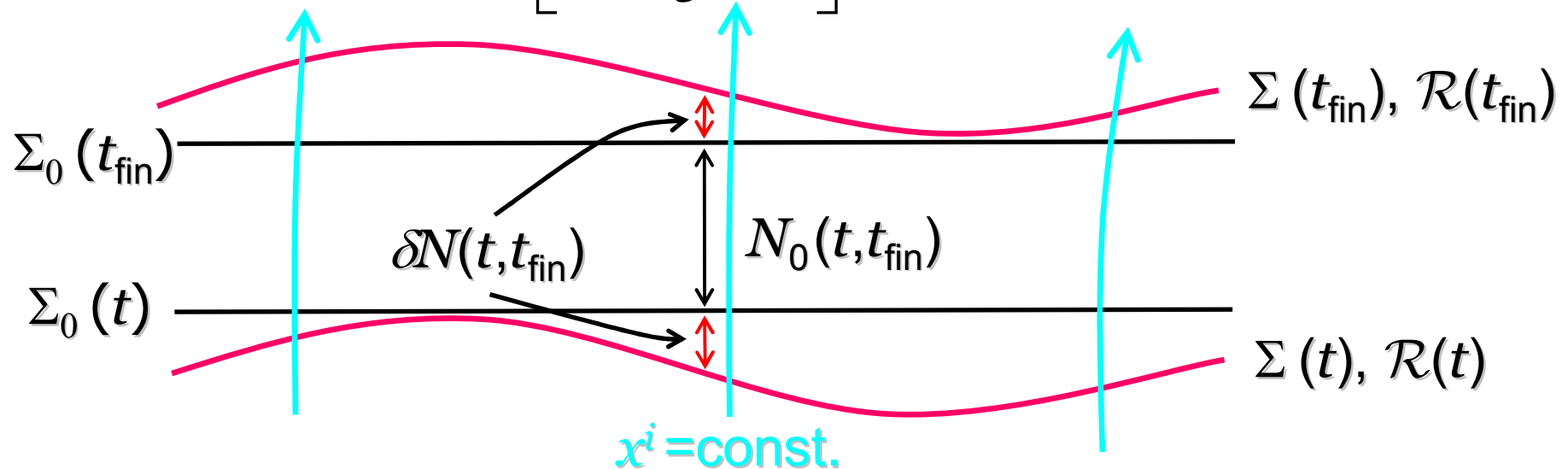
δN formula

MS & Stewart '96

- perturbation in # of e-folds between $\Sigma(t)$ and $\Sigma(t_{\text{fin}})$:

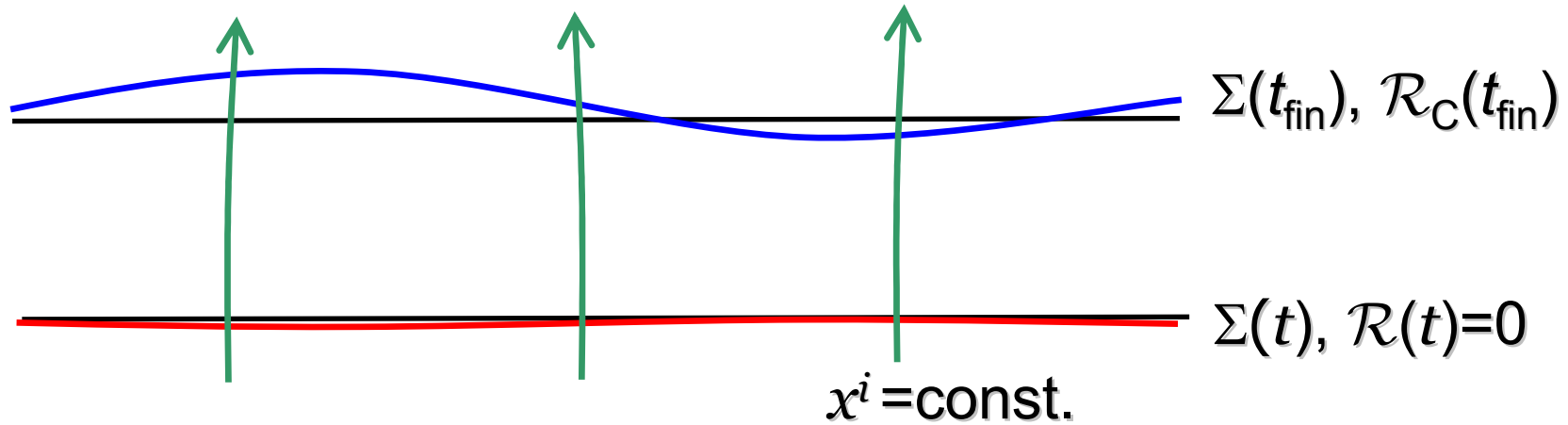
$$\delta N(t; t_{\text{fin}}) \equiv \int_t^{t_{\text{fin}}} \tilde{H} d\tau - \left(\int_t^{t_{\text{fin}}} H d\tau \right)_{\text{background}} \quad \varepsilon = \frac{\text{horizon size}}{\text{wavelength}}$$

$$= \int_t^{t_{\text{fin}}} \partial_t \left[\mathcal{R} + \frac{1}{3} \Delta^{(3)} E \right] dt = \mathcal{R}(t_{\text{fin}}) - \mathcal{R}(t) + O(\varepsilon^2)$$



$\delta N=0$ if both $\Sigma(t)$ and $\Sigma(t_{\text{fin}})$ are chosen to be 'flat' ($\mathcal{R}=0$).

Choose $\Sigma(t) = \text{flat}$ ($\mathcal{R}=0$) and $\Sigma(t_{\text{fin}}) = \text{comoving}$:



$$\Rightarrow \delta N(t; t_{\text{fin}}) = \mathcal{R}_C(t_{\text{fin}})$$

↑ curvature perturbation on comoving slice
(suffix 'C' for comoving)

The gauge-invariant variable ' ζ ' used in the literature is equal to \mathcal{R}_C on superhorizon scales (sometimes $\zeta = -\mathcal{R}_C$)

- by definition, $\delta N(t; t_{\text{fin}})$ is t -independent.
- important to keep in mind that δN is a non-local quantity

2. Non-linear extension

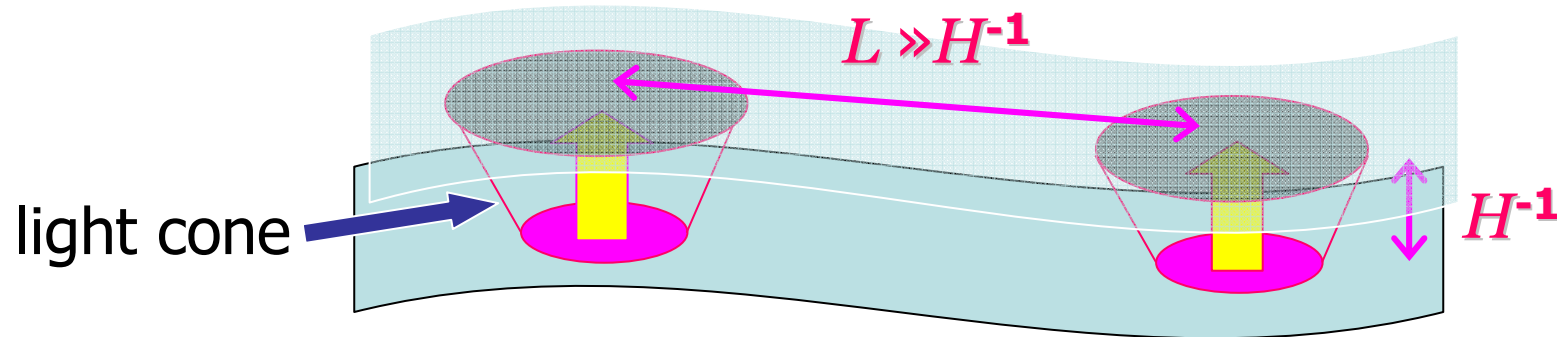
Lyth, Malik & MS ('05)

- On superhorizon scales, gradient expansion is valid:

$$\left| \frac{\partial}{\partial x^i} Q \right| \ll \left| \frac{\partial}{\partial t} Q \right| \sim HQ; \quad H \sim \sqrt{G\rho}$$

Belinski et al. '70, Tomita '72, Salopek & Bond '90, ...

This is a consequence of causality:



- At lowest order, no signal propagates in spatial directions.

Field equations reduce to ODE's

➤ metric on superhorizon scales

- gradient expansion:

$$\partial_i \rightarrow \varepsilon \hat{\partial}_i, \quad \varepsilon = \text{expansion parameter}$$

- metric:

$$ds^2 = -\mathcal{N}^2 dt^2 + e^{2\alpha} \tilde{\gamma}_{ij} (dx^i + \beta^i dt)(dx^j + \beta^j dt)$$

$$\det \tilde{\gamma}_{ij} = 1, \quad \beta^i = O(\varepsilon)$$

↑ the only non-trivial assumption
contains GW (\sim tensor) modes

$$e^{\alpha(t, x^i)} = a(t) e^{\mathcal{R}(t, x^i)}; \quad \mathcal{R} \sim \text{curvature perturbation}$$

↑
fiducial 'background'

e.g., choose $\mathcal{R}(t_*, 0) = 0$

- Local Friedmann equation & δN formula

$$\tilde{H}^2(t, x^i) = \frac{8\pi G}{3} \rho(t, x^i) + O(\varepsilon^2)$$

$$\tilde{H} \equiv \frac{\partial}{\partial \tau} \alpha = \frac{\partial}{\mathcal{N} \partial t} [\ln a + \mathcal{R}]$$

x^i : comoving (Lagrangian) coordinates.

$d\tau = \mathcal{N} dt$: proper time along fluid flow

$$\frac{d}{d\tau} \rho + 3\tilde{H}(\rho + p) = 0$$

$$\tilde{H} \equiv -\frac{1}{3(\rho + p)} \frac{\partial}{\partial \tau} \rho$$

exactly the same as the background equations.

$$N(t_2, t_1) = \int_{t_1}^{t_2} \tilde{H} d\tau = N_o(t_2, t_1) + \mathcal{R}(t_2, x^i) - \mathcal{R}(t_1, x^i)$$

... same as linear theory

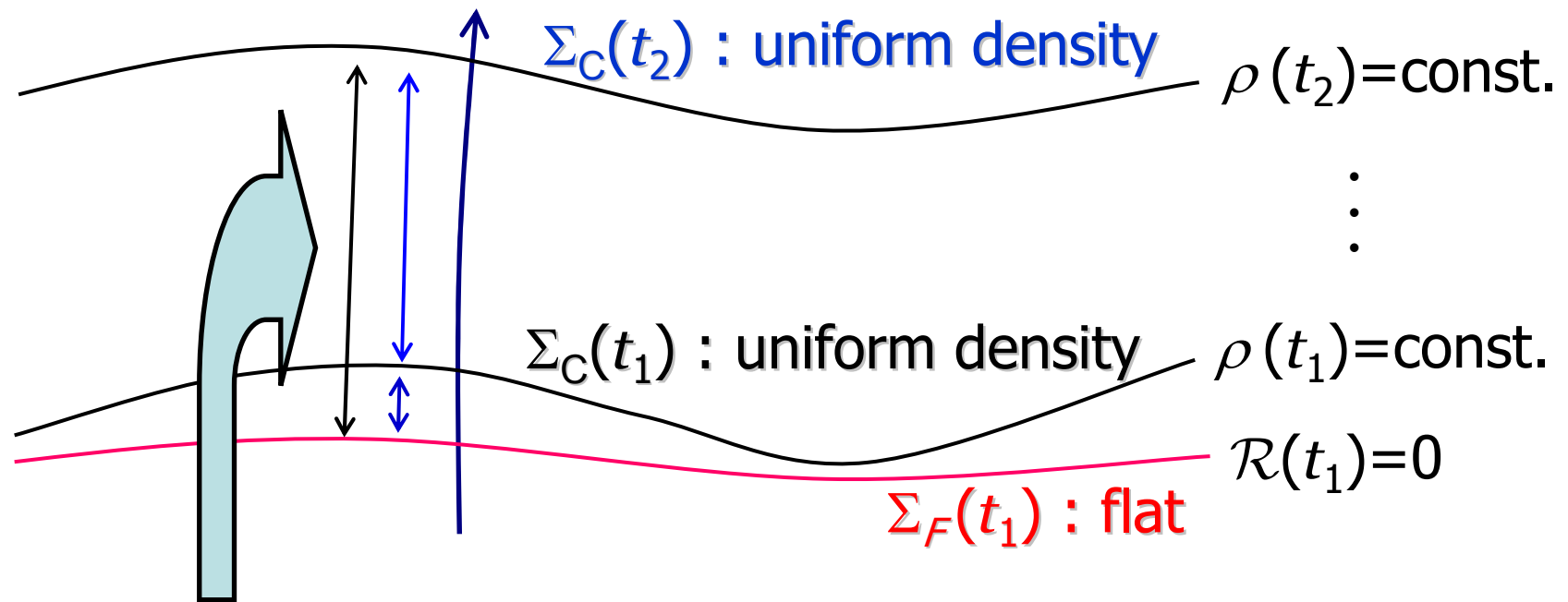
$$N_o(t_2, t_1) = \ln[a(t_2)/a(t_1)]$$

$$N(t_2, t_1) = -\int_{t_1}^{t_2} dt \frac{1}{3(\rho + p)} \frac{\partial \rho}{\partial t}$$

➤ δN - formula

Choose slicing such that slice is **flat at $t = t_1$ [$\Sigma_F(t_1)$]**
and **uniform density (=comoving) at $t = t_2$ [$\Sigma_C(t_1)$]** :

('flat' slice: $\Sigma(t)$ on which $\mathcal{R} = 0 \Leftrightarrow e^\alpha = a(t)$)



$$\begin{aligned} N(\Sigma_C(t_2), \Sigma_F(t_1)) &\equiv N_0(t_2, t_1) + \delta N_F(t_2, t_1; x^i) \\ &= N(\Sigma_C(t_2), \Sigma_C(t_1)) + N(\Sigma_C(t_1), \Sigma_F(t_1)) \end{aligned}$$

Then

$$\mathcal{R}(t_2, x^i) - \mathcal{R}(t_1, x^i) = \mathcal{R}_C(t_2, x^i) = \delta N_F(t_2, t_1; x^i)$$

||
comoving

suffix C for comoving (=uniform ρ)

where

$$\delta N_F(t_2, t_1; x^i) + N_o(t_2, t_1) = -\frac{1}{3} \int_{\Sigma_F(t_1)}^{\Sigma_C(t_2)} \frac{\partial_t \rho}{\rho + P} \Big|_{x^i} dt$$

This reduces in linear theory to

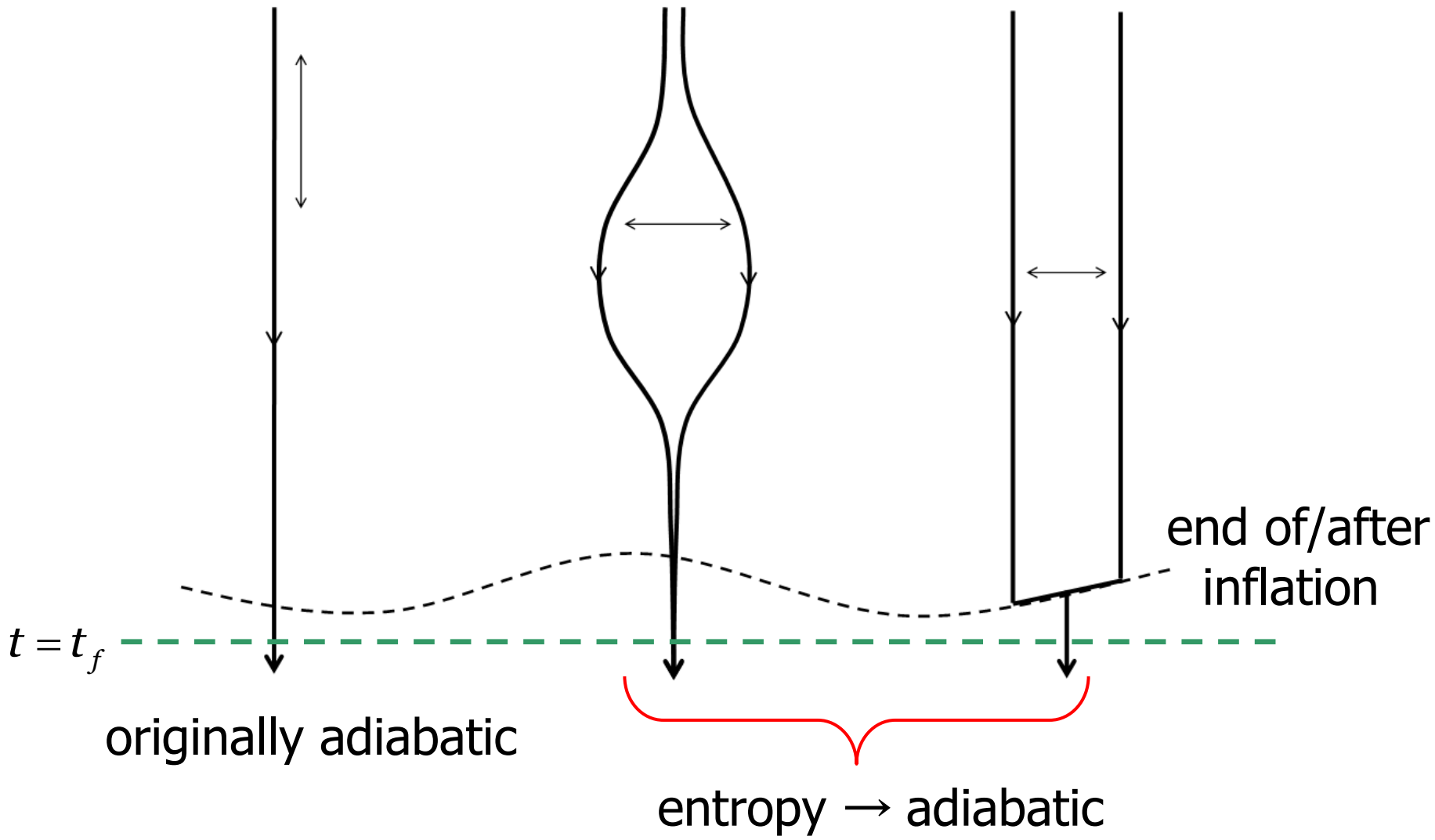
$$\mathcal{R}_C(t_2) = \delta N_F(t_1; t_2) = \left[\sum_a \frac{\partial N}{\partial \phi^a} \delta \phi_F^a(t_1) \right]$$

N.B. In general $\delta N_F \neq N(\Sigma_C(t_1), \Sigma_F(t_1); x^i)$

$$\Leftrightarrow N(\Sigma_C(t_2), \Sigma_C(t_1); x^i) \equiv -\frac{1}{3} \int_{\Sigma_C(t_1)}^{\Sigma_C(t_2)} \frac{\partial_t \rho}{\rho + P} \Big|_{x^i} dt \neq N_o(t_2, t_1)$$

because \mathcal{R}_C is not conserved in general

3 types of δN



3. δN for inflation at 'attractor' stage

MS & Tanaka ('98), Lyth & Rodriguez ('05),...

- In slow-roll inflation or inflation at an **attractor** stage, all decaying mode solutions of the (multi-comp) inflaton field ϕ have died out.
- If ϕ is in an attractor regime when the scale of our interest leaves the horizon, $d\phi/dt$ will be a function of ϕ . Hence **# of e-folds is only a function of ϕ** , no matter how complicated the subsequent evolution may be.

$$N = N\left(\phi, \frac{d\phi}{dt}\right), \quad \frac{d\phi}{dt} = f(\phi) \quad \Longrightarrow \quad N = N(\phi)$$

- Nonlinear δN for multi-component inflation :

$$\begin{aligned}\delta N &= N(\phi^A + \delta\phi^A) - N(\phi^A) \\ &= \sum_n \frac{1}{n!} \frac{\partial^n N}{\partial\phi^{A_1} \partial\phi^{A_2} \dots \partial\phi^{A_n}} \delta\phi^{A_1} \delta\phi^{A_2} \dots \delta\phi^{A_n}\end{aligned}$$

where $\delta\phi = \delta\phi_F$ (on flat slice) at horizon-crossing.

$\delta\phi_F$ may contain non-gaussianity from
subhorizon (quantum) interactions

eg, in DBI inflation

4. Conservation of nonlinear \mathcal{R}_c

For adiabatic fluid: $p = p(\rho)$, $\nabla_\alpha T^{\alpha\beta} = 0$

Lyth, Malik & MS ('05)

$$\begin{aligned} N(t_2, t_1; x^i) &= -\frac{1}{3} \int_{t_1}^{t_2} \frac{\partial_t \rho}{\rho + P(\rho)} dt \\ &= -\frac{1}{3} \int_{\rho(t_1, x^i)}^{\rho(t_2, x^i)} \frac{d\rho}{\rho + P(\rho)} = \mathcal{R}(t_2, x^i) - \mathcal{R}(t_1, x^i) + \ln \left[\frac{a(t_2)}{a(t_1)} \right] \end{aligned}$$



$$\zeta_{NL}(x^i) \equiv \mathcal{R}(t, x^i) + \frac{1}{3} \int_{\rho(t)}^{\rho(t, x^i)} \frac{d\rho}{\rho + P(\rho)}$$

\mathcal{R} and ρ can be evaluated on any time slice

... slice-independent

r.h.s. = \mathcal{R}_c for $\rho = \text{const}$ slice $\longrightarrow \zeta_{NL} = \mathcal{R}_c$

➤ applicable to **each decoupled fluid**

example: $\rho = \sum_a^N \rho_a$; $p_a = w_a \rho_a$, $w_a = \text{const.}$
 (N decoupled perfect fluids)

\mathcal{R} on uniform ρ_a

$$\begin{aligned} \mathcal{R}_a(x^i) &= \mathcal{R}_{\text{tot}}(t, x^i) + \int_{\bar{\rho}_a(t)}^{\rho_a(t, x^i)} \frac{d\rho_a}{3(1+w_a)\rho_a} \\ &= \mathcal{R}_{\text{tot}}(t, x^i) + \frac{1}{3(1+w_a)} \ln \frac{\rho_a(t, x^i)}{\bar{\rho}_a(t)} \end{aligned}$$

$$\Rightarrow \rho_a(t, x^i) = \bar{\rho}_a(t) \exp \left[3(1+w_a) \left(\mathcal{R}_a(x^i) - \mathcal{R}_{\text{tot}}(t, x^i) \right) \right]$$

$$\begin{aligned} \Rightarrow \rho(t) &= \sum_a \rho_a(t, x^i) \\ &= \sum_a \bar{\rho}_a(t) \exp \left[3(1+w_a) \left(\mathcal{R}_a(x^i) - \mathcal{R}_{\text{C,tot}}(t, x^i) \right) \right] \end{aligned}$$

uniform density slice

nonlinear version of

$$\mathcal{R}_{\text{C,tot}}(t, x^i) = \frac{\sum_a (1+w_a) \rho_a(t) \mathcal{R}_a(x^i)}{\sum_a (1+w_a) \rho_a(t)}$$

Scalar field: $P=P(\rho)$?

Naruko & MS ('11)

- For a scalar field, this (adiabaticity) condition is non-trivial.

$$S_\phi = \int d^4x \sqrt{-g} [W(X, \phi) - G(X, \phi) \square \phi]; \quad X \equiv -\frac{1}{2} g^{\mu\nu} \partial_\mu \phi \partial_\nu \phi$$

canonical: $W = X, G = 0$

$$\rho = \frac{1}{2} \left(\frac{d\phi}{d\tau} \right)^2 + V(\phi), \quad p = \frac{1}{2} \left(\frac{d\phi}{d\tau} \right)^2 - V(\phi)$$

$d\tau = \mathcal{N} dt$, \mathcal{N} : lapse

k-essence: $G = 0$

$$\rho = \frac{1}{2} \left(\frac{d\phi}{d\tau} \right)^2 W_{,X} - W, \quad p = W(X, \phi) \quad X = \frac{1}{2} \left(\frac{d\phi}{d\tau} \right)^2$$

Galileon: $G_{,X} \neq 0$

very complicated...

Field eqn : $\delta S_\phi = 0$

$$-\frac{1}{\sqrt{\gamma}} \partial_\tau \left(\sqrt{\gamma} \left[(W_{,X} - G_{,\phi}) \partial_\tau \phi - G_{,X} (\square \phi \partial_\tau \phi + \partial_\tau X) \right] \right) + W_{,\phi} - G_{,\phi} \square \phi = 0,$$

$G = 0$:

Neglecting spatial derivatives, field eqn. becomes

$$\boxed{\left[W_{,X} + W_{,XX} (\partial_\tau \phi)^2 \right] \partial_\tau^2 \phi + W_{,X\phi} (\partial_\tau \phi)^2 - W_{,\phi}} + K \boxed{W_{,X} \partial_\tau \phi} = 0$$

$$A(\phi) \partial_\tau^2 \phi \quad K = \partial_\tau \ln \sqrt{g^{(3)}} = 3\tilde{H} = 3\partial_\tau (\ln a + \mathcal{R}) \quad B(\phi)$$

If in an attractor regime: $\frac{\partial \phi}{\partial \tau} \left(= \frac{\partial \phi}{\mathcal{N} \partial t} \right) = f(\phi)$

$$A(\phi) \partial_\tau \phi + K B(\phi) = 0$$

$$\Rightarrow K = -\frac{A(\phi) \partial_\tau \phi}{B(\phi)}$$



$$\text{same as } K = -\frac{\partial_\tau \rho}{\rho + p(\rho)}$$

$$\begin{aligned}
N(t_2, t_1; x^i) &= \frac{1}{3} \int_{t_1}^{t_2} d\tau K = N_o(t_2, t_1) + \mathcal{R}(t_2, x^i) - \mathcal{R}(t_1, x^i) \\
&= - \int_{t_1}^{t_2} d\tau \frac{\partial_\tau \phi A(\phi)}{3B(\phi)} = - \int_{\phi_1}^{\phi_2} d\phi \frac{A(\phi)}{3B(\phi)} \equiv F(\phi_2) - F(\phi_1)
\end{aligned}$$

- conservation of “slice-independent” NL curvature perturbation

$$\zeta_{NL}(x^i) = \mathcal{R}(t, x^i) - \left[F(\phi(t, x^i)) - F(\phi_o(t)) \right]$$

... can be evaluated in any slicing

- In particular, for uniform ϕ (=comoving) slicing: $\phi = \phi_o(t)$

$$\zeta_{NL}(x^i) = \mathcal{R}_c(t, x^i) = \mathcal{R}_c(x^i)$$

valid for “any” theory of gravity

valid for each decoupled scalar field

$G_{,X} \neq 0 :$

Field equation

$$\begin{aligned} & \left(W_{,X} - 2G_{,\phi} + 2G_{,X}K\partial_\tau\phi \right) \partial_\tau^2\phi + G_{,X}(\partial_\tau K + K^2)(\partial_\tau\phi)^2 \\ & + (\partial_\tau G_{,X})K(\partial_\tau\phi)^2 + \left[\partial_\tau(W_{,X} - G_{,\phi}) + K(W_{,X} - 2G_{,\phi}) \right] \partial_\tau\phi - W_{,\phi} = 0 \end{aligned}$$

- appears **2nd time** derivative of the metric ($\sim \partial_\tau K$),
→ **cannot** show the conservation w/o using Einstein eqns.
- if we invoke **Einstein eqns**, we can replace $\partial_\tau K$ with K

$$\Rightarrow A(\phi)\partial_\tau\phi + K B(\phi) = 0 \quad \text{at attractor stage}$$

conservation of NL curvature perturbation can be shown only after gravitational equations are used.

ie, **valid only if ϕ dominates the universe**

8. Summary

- There exists **non-linear generalization of δN formula**, which may be useful in evaluating non-Gaussianity /nonlinearity from inflation.
- There exists non-linear generalization of **conserved \mathcal{R}_c for adiabatic perturbation** on superhorizon scales.
 - conservation law applies to **each decoupled fluid**
 - applies also to **each decoupled scalar field** provided field eqn contains only 1st time derivative of the metric.
 - for a galieon-type field, which contains 2nd time derivative, the use of gravitational eqn are necessary to show the conservation.